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CONTROL SYSTEM

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Lesson 2

# Basics of Laplace Transform

## Basics of Laplace Transform

### Objectives:

At the end of this lesson, students will be able to:

1. Use Laplace Transform in solving differential equations of Control System.

### Basics of Laplace Transform

The transformation technique relating the time functions to frequency dependent functions of a complex variable is called the **Laplace transformation technique**. Such transformation is very useful in solving linear differential equations.

### Definition of Laplace Transform

The Laplace transform is defined as below :

Let  $f(t)$  be a real function of a real variable  $t$  defined for  $t > 0$ , then

$$F(s) = L\{f(t)\} = \int_0^{\infty} f(t) \cdot e^{-st} dt$$

where  $F(s)$  is called Laplace transform of  $f(t)$ . And the variable 's' which appears in  $F(s)$  is frequency dependent complex variable.

The time function  $f(t)$  is obtained back from the Laplace transform by a process called Inverse Laplace transform and denoted as  $L^{-1}$ .

$$L^{-1} [F(s)] = L^{-1} \{L\{f(t)\}\} = f(t)$$

►► **Example 2.1** : Find the Laplace transform of  $e^{-at}$  and 1 for  $t \geq 0$ .

**Solution** : i)  $f(t) = e^{-at}$

$$\begin{aligned} F(s) = L\{f(t)\} &= \int_0^{\infty} f(t) e^{-st} dt = \int_0^{\infty} e^{-at} \cdot e^{-st} dt \\ &= \int_0^{\infty} e^{-(s+a)t} dt = \left[ -\frac{1}{(s+a)} \cdot e^{-(s+a)t} \right]_0^{\infty} \\ &= 0 - \left( \frac{-1}{s+a} \right) = \frac{1}{s+a} \end{aligned}$$

$$\therefore L\{e^{-at}\} = \frac{1}{s+a} \quad \text{and} \quad L^{-1}\left\{\frac{1}{s+a}\right\} = e^{-at}$$

$$(ii) \quad f(t) = 1$$

$$\therefore F(s) = \int_0^{\infty} f(t) e^{-st} dt = \int_0^{\infty} e^{-st} dt = \left[ \frac{e^{-st}}{-s} \right]_0^{\infty} = \frac{1}{s}$$

$$\therefore L\{1\} = \frac{1}{s} \quad \text{and} \quad L^{-1}\left\{\frac{1}{s}\right\} = 1$$

## Properties of Laplace Transform

### 1. Linearity

So if  $F_1(s)$ ,  $F_2(s)$ , .....,  $F_n(s)$  are the Laplace transforms of the time functions  $f_1(t)$ ,  $f_2(t)$ , .....,  $f_n(t)$  respectively then,

$$L\{f_1(t) + f_2(t) + \dots + f_n(t)\} = F_1(s) + F_2(s) + \dots + F_n(s)$$

### 2. Scaling Theorem

$$L\{K f(t)\} = K F(s)$$

... K is constant

### 3. Real Differentiation

Let  $F(s)$  be the Laplace transform of  $f(t)$ . Then,

$$L\left\{\frac{d f(t)}{dt}\right\} = s F(s) - f(0^-)$$

where  $f(0^-)$  indicates value of  $f(t)$  at  $t = 0^-$  i.e. just before the instant  $t = 0$

The theorem can be extended for  $n^{\text{th}}$  order derivative as,

$$L\left\{\frac{d^n f(t)}{dt^n}\right\} = s^n F(s) - s^{n-1} f(0^-) - s^{n-2} f'(0^-) - \dots - f^{(n-1)}(0^-)$$

where  $f^{(n-1)}(0^-)$  is the value of  $(n-1)^{\text{th}}$  derivative of  $f(t)$  at  $t = 0^-$ .

i.e for  $n = 2$ ,  $L\left\{\frac{d^2 f(t)}{dt^2}\right\} = s^2 F(s) - s f(0^-) - f'(0^-)$

for  $n = 3$ ,  $L\left\{\frac{d^3 f(t)}{dt^3}\right\} = s^3 F(s) - s^2 f(0^-) - s f'(0^-) - f''(0^-)$  and so on.

### 4. Real Integration

If  $F(s)$  is the Laplace transform of  $f(t)$  then,

$$L\left\{\int_0^t f(t) dt\right\} = \frac{F(s)}{s}$$

## 5. Differentiation by S

$$\boxed{L\{t f(t)\} = -\frac{dF(s)}{ds}}$$

Thus,  $L\{t\} = L\{t \times 1\} = -\frac{d}{ds} [L\{1\}] = -\frac{d}{ds} \left[ \frac{1}{s} \right] = \frac{1}{s^2} = \frac{1!}{s^{1+1}}$

$$L\{t^2\} = L\{t \times t\} = -\frac{d}{ds} [L\{t\}] = -\frac{d}{ds} \left[ \frac{1}{s^2} \right] = \frac{2}{s^3} = \frac{2!}{s^{2+1}}$$

## 6. Complex Translation

$$\boxed{F(s - a) = L\{e^{at} f(t)\}}$$

and

$$\boxed{F(s + a) = L\{e^{-at} f(t)\}}$$

$$\boxed{F(s \mp a) = F(s) \Big|_{s = s \mp a}}$$

where  $F(s)$  is the Laplace transform of  $f(t)$ .

## 7. Real Translation (Shifting Theorem)

This theorem is useful to obtain the Laplace transform of the shifted or delayed function of time.

If  $F(s)$  is the Laplace transform of  $f(t)$  then the Laplace transform of the function delayed by time  $T$  is,

$$\boxed{L\{f(t-T)\} = e^{-Ts} F(s)}$$

## 8. Initial Value Theorem

The Laplace transform is very useful to find the initial value of the time function  $f(t)$ . Thus if  $F(s)$  is the Laplace transform of  $f(t)$  then,

$$\boxed{f(0^+) = \lim_{t \rightarrow 0^+} f(t) = \lim_{s \rightarrow \infty} s F(s)}$$

## 9. Final Value Theorem

$$\boxed{\lim_{t \rightarrow \infty} f(t) = \lim_{s \rightarrow 0} s F(s)}$$

**Table of Laplace Transforms :**

$f(t)$	$F(s)$
1	$\frac{1}{s}$
Constant K	$\frac{K}{s}$
K f(t), K is constant	K F(s)
t	$\frac{1}{s^2}$
$t^n$	$\frac{n!}{s^{n+1}}$
$e^{-at}$	$\frac{1}{s+a}$
$e^{at}$	$\frac{1}{s-a}$
$e^{-at} t^n$	$\frac{n!}{(s+a)^{n+1}}$

$\sin \omega t$	$\frac{\omega}{s^2 + \omega^2}$
$\cos \omega t$	$\frac{s}{s^2 + \omega^2}$
$e^{-at} \sin \omega t$	$\frac{\omega}{(s+a)^2 + \omega^2}$
$e^{-at} \cos \omega t$	$\frac{(s+a)}{(s+a)^2 + \omega^2}$
$\sinh \omega t$	$\frac{\omega}{s^2 - \omega^2}$
$\cosh \omega t$	$\frac{s}{s^2 - \omega^2}$
$t e^{-at}$	$\frac{1}{(s+a)^2}$
$1 - e^{-at}$	$\frac{a}{s(s+a)}$

Function $f(t)$	Laplace Transform $F(s)$
Unit step = $u(t)$	$\frac{1}{s}$
$A u(t)$	$\frac{A}{s}$
Delayed unit step = $u(t - T)$	$\frac{e^{-Ts}}{s}$
$A u(t - T)$	$\frac{A e^{-Ts}}{s}$
Unit ramp = $r(t) = t u(t)$	$\frac{1}{s^2}$
$A t u(t)$	$\frac{A}{s^2}$
Delayed unit ramp = $r(t - T) = (t - T) u(t - T)$	$\frac{e^{-Ts}}{s^2}$
$A (t - T) u(t - T)$	$\frac{A e^{-Ts}}{s^2}$
Unit impulse = $\delta(t)$	1
Delayed unit impulse = $\delta(t - T)$	$e^{-Ts}$
Impulse of strength K i.e. $K \delta(t)$	K

## Inverse Laplace Transform

As mentioned earlier, inverse Laplace transform is calculated by partial fraction method rather than complex integration evaluation. Let  $F(s)$  is the Laplace transform of  $f(t)$  then the inverse Laplace transform is denoted as,

$$f(t) = L^{-1} [F(s)]$$

The  $F(s)$ , in partial fraction method, is written in the form as,

$$F(s) = \frac{N(s)}{D(s)}$$

where  $N(s)$  = Numerator polynomial in  $s$

and  $D(s)$  = Denominator polynomial in  $s$

The given function  $F(s)$  can be expressed in partial fraction form only when degree of  $N(s)$  is less than  $D(s)$ . Hence if degree of  $N(s)$  is equal or higher than  $D(s)$  then mathematically divide  $N(s)$  by  $D(s)$  to express  $F(s)$  in quotient and remainder form as,

$$F(s) = Q + F_1(s) = Q + \frac{N'(s)}{D'(s)}$$

where  $Q =$  Quotient obtained by dividing  $N(s)$  by  $D(s)$

and  $F_1(s) = \frac{N'(s)}{D'(s)} =$  Remainder

There are 3 types of  $D(s)$ :

### 1. Simple and Real Roots

The roots of  $D(s)$  are simple and real. Hence the function  $F(s)$  can be expressed as,

$$F(s) = \frac{N(s)}{D(s)} = \frac{N(s)}{(s-a)(s-b)(s-c) \dots}$$

►► **Example 2.2 :** Find the inverse Laplace transform of given  $F(s)$ .

$$F(s) = \frac{(s+2)}{s(s+3)(s+4)}$$

**Solution :** The degree of  $N(s)$  is less than  $D(s)$ . Hence  $F(s)$  can be expressed as,

$$F(s) = \frac{K_1}{s} + \frac{K_2}{(s+3)} + \frac{K_3}{(s+4)}$$

$$\text{where } K_1 = s \cdot F(s)|_{s=0} = s \cdot \frac{(s+2)}{s(s+3)(s+4)} \Big|_{s=0} = \frac{2}{3 \times 4} = \frac{1}{6}$$

$$K_2 = (s+3) \cdot F(s)|_{s=-3} = (s+3) \cdot \frac{(s+2)}{s(s+3)(s+4)} \Big|_{s=-3} = \frac{(-3+2)}{(-3)(-3+4)} = \frac{1}{3}$$

$$K_3 = (s+4) \cdot F(s)|_{s=-4} = (s+4) \cdot \frac{(s+2)}{s(s+3)(s+4)} \Big|_{s=-4} = \frac{(-4+2)}{(-4)(-4+3)} = -\frac{1}{2}$$

$$\therefore F(s) = \frac{1/6}{s} + \frac{1/3}{(s+3)} - \frac{1/2}{(s+4)}$$

Taking inverse Laplace transform,

$$\therefore f(t) = \frac{1}{6} + \frac{1}{3} e^{-3t} - \frac{1}{2} e^{-4t}$$



## 2. Multiple Roots

The given function is of the form,

$$F(s) = \frac{N(s)}{(s-a)^n D'(s)}$$

►►► **Example 2.3 :** Obtain the inverse Laplace transform of given  $F(s)$ .

$$F(s) = \frac{(s-2)}{s(s+1)^3}$$

**Solution :** The given  $F(s)$  can be expressed as,

$$F(s) = \frac{K_0}{(s+1)^3} + \frac{K_1}{(s+1)^2} + \frac{K_2}{(s+1)} + \frac{K_3}{s}$$

Finding L.C.M. of right hand side,

$$\frac{(s-2)}{s(s+1)^3} = \frac{K_0(s) + K_1(s+1)s + K_2(s+1)^2 s + K_3(s+1)^3}{s(s+1)^3}$$

$$\therefore (s-2) = K_0s + K_1s^2 + K_1s + K_2s^3 + 2K_2s^2 + K_2s + K_3s^3 + 3K_3s^2 + 3K_3s + K_3$$

Comparing coefficients of various powers of  $s$  on both sides,

$$\text{for } s^3, \quad K_2 + K_3 = 0 \quad \dots (1)$$

$$\text{for } s^2, \quad K_1 + 2K_2 + 3K_3 = 0 \quad \dots (2)$$

$$\text{for } s^1, \quad K_0 + K_1 + K_2 + 3K_3 = 1 \quad \dots (3)$$

$$\text{for } s^0, \quad K_3 = -2 \quad \dots (4)$$

$$\text{As } K_3 = -2$$

$$\text{from (1), } K_2 = 2$$

$$\therefore \text{ from (2), } K_1 = 2$$

$$\therefore \text{ from (3), } K_0 = 3$$

$$\therefore F(s) = \frac{3}{(s+1)^3} + \frac{2}{(s+1)^2} + \frac{2}{(s+1)} - \frac{2}{s}$$

$$\text{Now } L[e^{-at} t^n] = \frac{n!}{(s+a)^{n+1}}$$

$$\therefore L^{-1}\left[\frac{1}{(s+a)^{n+1}}\right] = \frac{e^{-at} t^n}{n!}$$

$$\therefore F(s) = 3 \cdot \frac{1}{(s+1)^3} + 2 \cdot \frac{1}{(s+1)^2} + 2 \cdot \frac{1}{(s+1)} - 2 \cdot \frac{1}{s}$$

$$\therefore f(t) = L^{-1} [F(s)] = \frac{3}{2!} e^{-t} \cdot t^2 + \frac{2}{1!} e^{-t} \cdot t + 2 e^{-t} - 2$$

$$\therefore f(t) = \frac{3}{2} t^2 e^{-t} + 2 t e^{-t} + 2 e^{-t} - 2$$

### 3. Complex Conjugate Roots

If there exists a quadratic term in  $D(s)$  of  $F(s)$  whose roots are complex conjugates then the  $F(s)$  is expressed with a first order polynomial in  $s$  in the numerator as,

$$F(s) = \frac{As + B}{(s^2 + \alpha s + \beta)} + \frac{N'(s)}{D'(s)}$$

where  $(s^2 + \alpha s + \beta)$  is the quadratic whose roots are complex conjugates while  $\frac{N'(s)}{D'(s)}$  represents remaining terms of the expansion. The  $A$  and  $B$  are partial fraction coefficients.

Consider  $F_1(s) = \frac{As + B}{s^2 + \alpha s + \beta}$        $A$  and  $B$  are known

Now complete the square in the denominator by calculating last term as,

$$L.T. = \frac{(M.T.)^2}{4(F.T.)}$$

where       $L.T =$  Last term

$M.T =$  Middle term

$F.T =$  First term

$$\therefore L.T. = \frac{\alpha^2}{4}$$

$$\therefore F_1(s) = \frac{As + B}{s^2 + \alpha s + \frac{\alpha^2}{4} + \beta - \frac{\alpha^2}{4}} = \frac{As + B}{\left(s + \frac{\alpha}{2}\right)^2 + \omega^2}$$

where       $\omega = \sqrt{\beta - \frac{\alpha^2}{4}}$

Now adjust the numerator  $As + B$  in such a way that it is of the form,

$$L [e^{-at} \sin \omega t] = \frac{\omega}{(s+a)^2 + \omega^2} \quad \text{or} \quad L [e^{-at} \cos \omega t] = \frac{(s+a)}{(s+a)^2 + \omega^2}$$

**Key Point:** Thus inverse Laplace transform of  $F(s)$  having complex conjugate roots of  $D(s)$ , always contains sine, cosine or damped sine or damped cosine functions.

►► **Example 2.4** : Find the inverse Laplace transform of

$$F(s) = \frac{s^2 + 3}{(s^2 + 2s + 5)(s + 2)}$$

**Solution** : The given  $F(s)$  can be written as,

$$F(s) = \frac{As + B}{s^2 + 2s + 5} + \frac{C}{s + 2}$$

as  $s^2 + 2s + 5$  has complex conjugate roots. To find  $A$ ,  $B$  and  $C$  find L.C.M. of right hand side,

$$\therefore F(s) = \frac{(s + 2)(As + B) + C(s^2 + 2s + 5)}{(s^2 + 2s + 5)(s + 2)}$$

$$\therefore \frac{s^2 + 3}{(s^2 + 2s + 5)(s + 2)} = \frac{As^2 + 2As + Bs + 2B + Cs^2 + 2sC + 5C}{(s^2 + 2s + 5)(s + 2)}$$

Comparing the coefficients of various powers of  $s$ , of the numerators of both sides

$$\therefore s^2 + 3 = s^2(A + C) + s(2A + B + 2C) + (2B + 5C)$$

$$\therefore A + C = 1 \quad \dots (1)$$

$$\therefore 2A + B + 2C = 0 \quad \dots (2)$$

$$\therefore 2B + 5C = 3 \quad \dots (3)$$

To solve the equations quickly, the coefficient  $C$  corresponding to the simple, real root can be obtained as,

$$\therefore C = F(s) \cdot (s + 2) \Big|_{s=-2} = \frac{(s^2 + 3)(s + 2)}{(s^2 + 2s + 5)(s + 2)} \Big|_{s=-2} = \frac{(4 + 3)}{(4 - 4 + 5)} = \frac{7}{5}$$

Substituting in (1) and (2),

$$A = -\frac{2}{5}$$

and  $B = -2$

$$\therefore F(s) = \frac{-\frac{2}{5}s - 2}{s^2 + 2s + 5} + \frac{7}{s + 2}$$

Consider  $F_1(s) = \frac{-\frac{2}{5}s - 2}{s^2 + 2s + 5}$

Completing square in the denominator,

$$\begin{aligned}
 F_1(s) &= \frac{-\frac{2}{5}s - 2}{s^2 + 2s + 1 + 5 - 1} = \frac{-\frac{2}{5}s - 2}{(s+1)^2 + (2)^2} = -\frac{2}{5} \left[ \frac{s+5}{(s+1)^2 + (2)^2} \right] \\
 &= -\frac{2}{5} \left[ \frac{s+1+4}{(s+1)^2 + (2)^2} \right] \quad \text{split 4 as } 2 \times 2 \\
 &= -\frac{2}{5} \left[ \frac{s+1}{(s+1)^2 + (2)^2} + 2 \times \frac{2}{(s+1)^2 + (2)^2} \right] \\
 \therefore F(s) &= -\frac{2}{5} \left\{ \frac{(s+1)}{(s+1)^2 + (2)^2} + 2 \cdot \frac{2}{(s+1)^2 + (2)^2} \right\} + \frac{7}{5}
 \end{aligned}$$

As 
$$L^{-1} \left[ \frac{(s+a)}{(s+a)^2 + \omega^2} \right] = [e^{-at} \cos \omega t] \quad \text{and}$$

$$L^{-1} \left[ \frac{\omega}{(s+a)^2 + \omega^2} \right] = [e^{-at} \sin \omega t]$$

Hence taking inverse Laplace transform of  $F(s)$ ,

$$f(t) = -\frac{2}{5} [e^{-t} \cos 2t + 2 e^{-t} \sin 2t] + \frac{7}{5} e^{-2t}$$

## Use of Laplace Transform in Control System

►►► **Example 2.5** : Obtain the expression for  $y(t)$  which is satisfying the differential equation  $\frac{d^2y(t)}{dt^2} + 6\frac{dy(t)}{dt} + 8y(t) = 16e^{-t}$ . Neglect initial conditions.

**Solution** : Taking Laplace transform of both sides of the given differential equation and neglecting initial condition terms in Laplace transform of  $\frac{d^2y(t)}{dt^2}$  and  $\frac{dy(t)}{dt}$  we get,

$$s^2Y(s) + 6sY(s) + 8Y(s) = \frac{16}{s+1}$$

$$\therefore (s^2 + 6s + 8) Y(s) = \frac{16}{(s+1)}$$

$$\therefore Y(s) = \frac{16}{(s+1)(s^2 + 6s + 8)}$$

$$\therefore Y(s) = \frac{16}{(s+1)(s+2)(s+4)}$$

$$\therefore Y(s) = \frac{a_1}{s+1} + \frac{a_2}{s+2} + \frac{a_3}{s+4}$$

$$\therefore Y(s) = \frac{5.33}{s+1} - \frac{8}{s+2} + \frac{2.66}{s+4}$$

Taking inverse Laplace transform of  $Y(s)$ ,

$$y(t) = 5.33 e^{-t} - 8 e^{-2t} + 2.66 e^{-4t}$$

This is the required solution of differential equation.

## Special Case of Inverse Laplace Transform

$$F(s) = \frac{P(s)}{Q(s)} \quad \dots \text{order of } P(s) \text{ and } Q(s) \text{ same}$$

$$= K + \frac{P'(s)}{Q(s)} \quad \dots \text{after dividing } P(s) \text{ by } Q(s)$$

Now Laplace inverse of constant term is impulse function. Refer last pair in the Table 2.2

$$\therefore L^{-1} [K] = K \delta(t) \quad \text{where } \delta(t) = \text{unit impulse.}$$

While  $P'(s) / Q(s)$  can now be expressed to obtain partial fraction expansion, to get its inverse very easily.

►►► **Example 2.6** : Find the Laplace inverse of  $F(s) = \frac{s^3 + 18s^2 + 3s + 5}{s^3 + 8s^2 + 17s + 10}$ .

**Solution** : Divide P(s) by Q(s).

$$\begin{array}{r} s^3 + 8s^2 + 17s + 10 \ ) \ s^3 + 18s^2 + 3s + 5 \ (1 \rightarrow K \\ \underline{s^3 + 8s^2 + 17s + 10} \\ 10s^2 - 14s - 5 \rightarrow P'(s) \end{array}$$

$$\begin{aligned} \therefore F(s) &= 1 + \frac{10s^2 - 14s - 5}{s^3 + 8s^2 + 17s + 10} \\ &= 1 + \frac{10s^2 - 14s - 5}{(s+2)(s+1)(s+5)} = 1 + \frac{A}{s+2} + \frac{B}{s+1} + \frac{C}{s+5} \end{aligned}$$

$$\therefore A = \left. \frac{10s^2 - 14s - 5}{(s+1)(s+5)} \right|_{s=-2} = -21$$

$$B = \left. \frac{10s^2 - 14s - 5}{(s+2)(s+5)} \right|_{s=-1} = 4.75$$

$$C = \left. \frac{10s^2 - 14s - 5}{(s+1)(s+2)} \right|_{s=-5} = 26.25$$

$$\therefore F(s) = 1 - \frac{21}{s+2} + \frac{4.75}{s+1} + \frac{26.25}{s+5}$$

$$\therefore f(t) = L^{-1}\{F(s)\} = \delta(t) - 21e^{-2t} + 4.75e^{-t} + 26.25e^{-5t}$$

where  $L^{-1}\{1\} = \delta(t) = \text{Unit impulse function.}$

►►► **Example 2.7** : Find the inverse Laplace transform of,

$$F(s) = \frac{2s+5}{s^2+5s+6}$$

(PTU, Jan.-2006)

**Solution** : Factorising denominator,

$$F(s) = \frac{2s+5}{(s+2)(s+3)} = \frac{A}{s+2} + \frac{B}{s+3}$$

... Partial fractions

$$A = F(s)(s+2) \Big|_{s=-2} = \frac{(-4+5)}{(3-2)} = 1$$

$$B = F(s)(s+3) \Big|_{s=-3} = \frac{(-6+5)}{(-3+2)} = 1$$

$$\therefore F(s) = \frac{1}{s+2} + \frac{1}{s+3}$$

$$\therefore f(t) = L^{-1}\{F(s)\} = e^{-2t} + e^{-3t}$$

Lesson 3

# Mathematical Modelling of Control System