



كلية المأمون الجامعة
قسم تقنيات الأشعة

المرحلة الثالثة

Equipment Techniques of
Magnetic Resonance Imaging

مدرس مساعد: عماد الربيعي

MSc Medical Imaging / MRI Applications

1st
Semester

Lecture 6

Gradient Coils (Spatial Encoding)

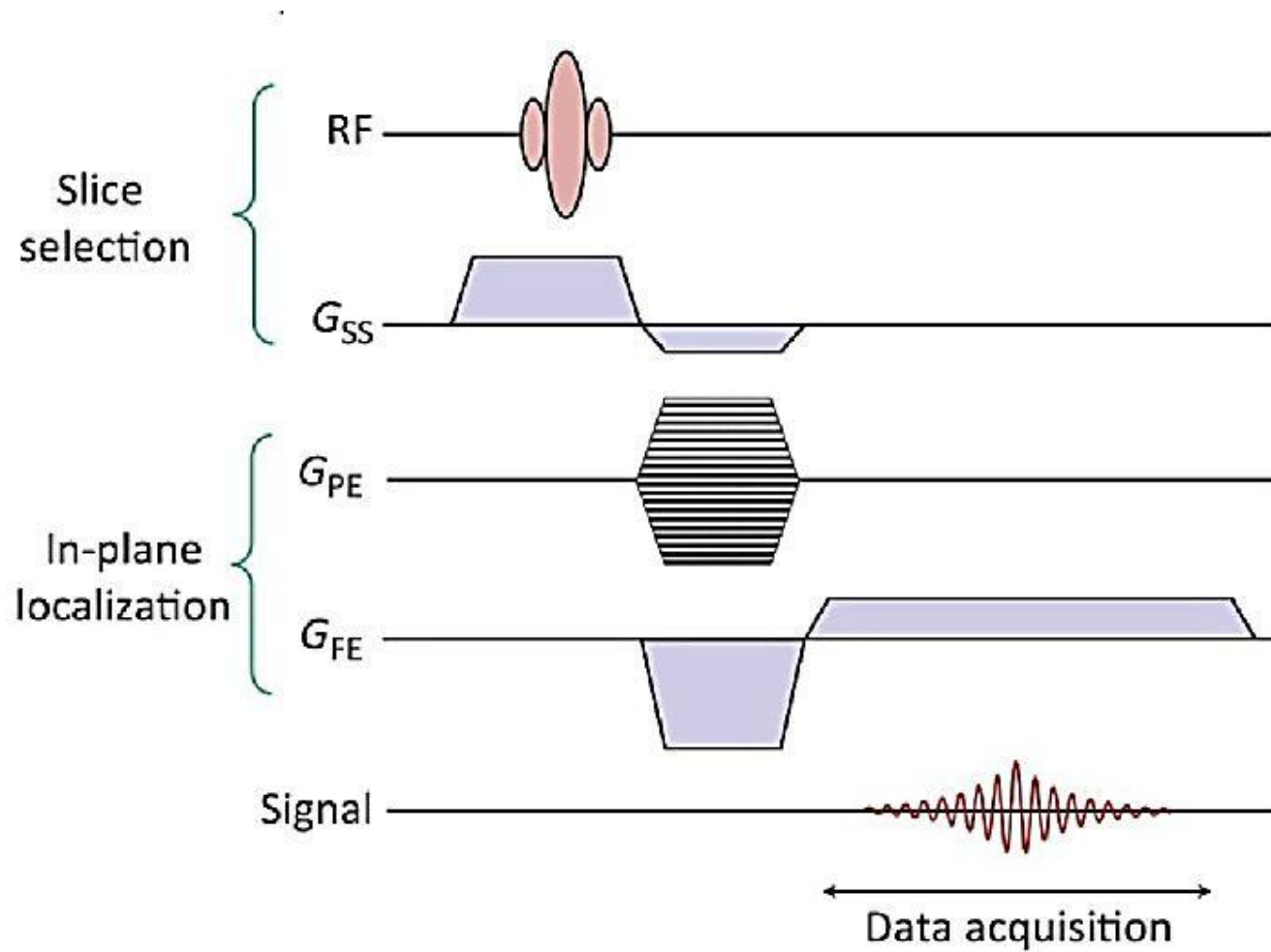
Larmor Equation: $\omega_0 = \gamma \cdot B_0$



Introduction

*Gradient coils are an essential component of magnetic resonance imaging (MRI) systems. These coils are used to create spatially varying magnetic fields within the MRI scanner, which allows for the encoding of spatial information in the MRI signal. There are three sets of gradient coils in an MRI system: the **x-gradient coil**, **y-gradient coil**, and **z-gradient coil**. Each set of coils is responsible for creating a magnetic field that varies along one of the three **spatial dimensions** (x, y, or z) within the imaging volume. By applying controlled currents to these gradient coils, the strength and direction of the magnetic field can be varied in a precise and controlled manner. This variation in magnetic field strength allows for **spatial encoding** of the MRI signal, which is essential for producing high-resolution images with detailed anatomical information.*

Larmor Equation: $\omega_0 = \gamma \cdot B_0$



Larmor Equation: $\omega_0 = \gamma \cdot B_0$

Head Lines

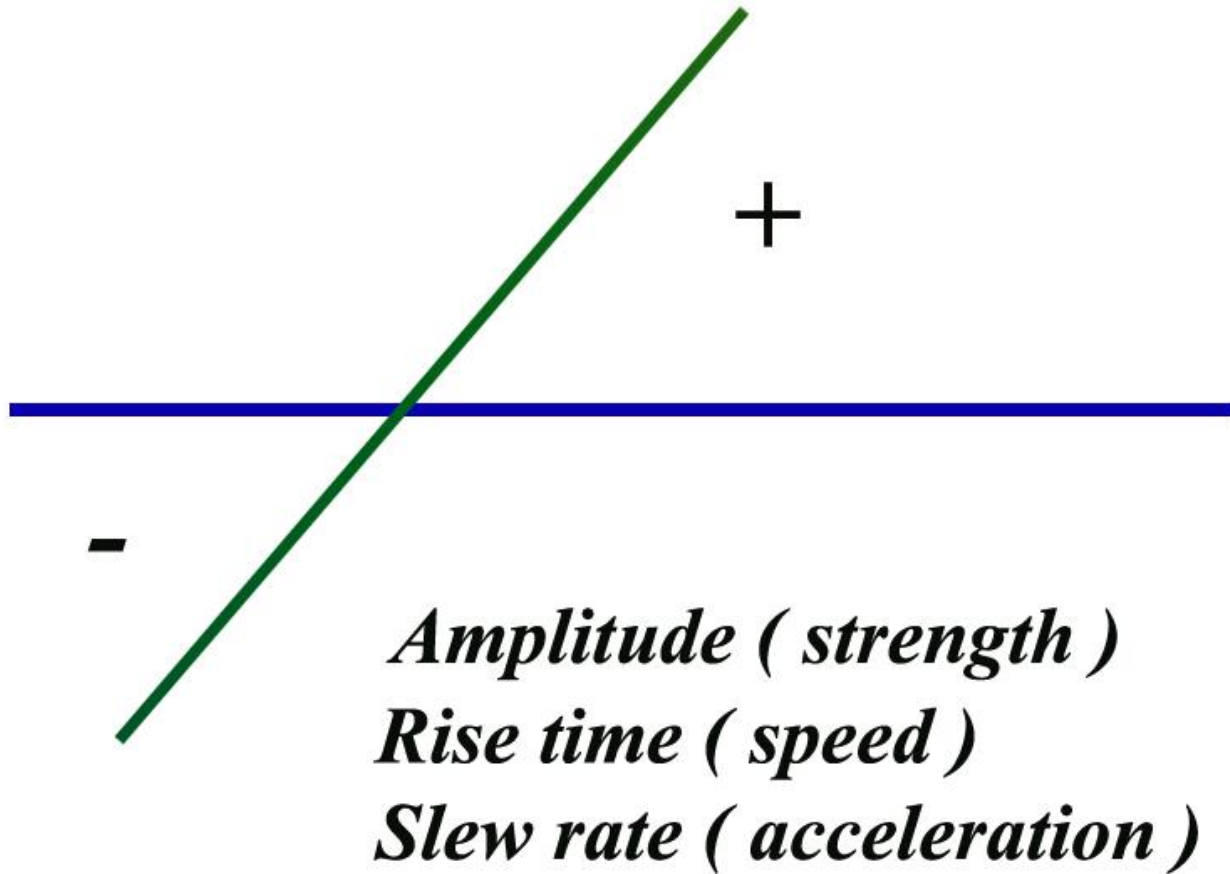
- *Gradient magnetic fields are superimposed over the primary magnetic field.*
- *Gradient magnetic fields are produced by applying **current** to the gradient coils.*
- *There are **three sets** of gradient coils in MR systems.*
- *The term **amplitude** refers to the severity of the slope of the gradient magnetic field (**strength** of the gradient system). The speed at which a gradient magnetic field attains its maximal amplitude is identified by its **rise time**.*
- *The maximal amplitude of gradient magnetic fields is described in units of millitesla per meter (mT / m).*

Larmor Equation: $\omega_0 = \gamma \cdot B_0$

- **Polarity** (either positive or negative) refers to whether the gradient magnetic field is creating a field greater than or less than the frequency of B_0 .
- To express gradient performance is slew rate.
- **Slew rate** refers to the acceleration of the gradient magnetic field to its maximal amplitude.
- Slew rate is expressed in units of Tesla/meter/second (T / m/sec).
- Currently, typical slew rates for gradient systems range from approximately **20 to over 200 T/m/sec**.

Slew rate = amplitude / rise time

Larmor Equation: $\omega_0 = \gamma \cdot B_0$



$$\text{Slew rate} = \text{amplitude} / \text{rise time}$$

Larmor Equation: $\omega_0 = \gamma \cdot B_0$

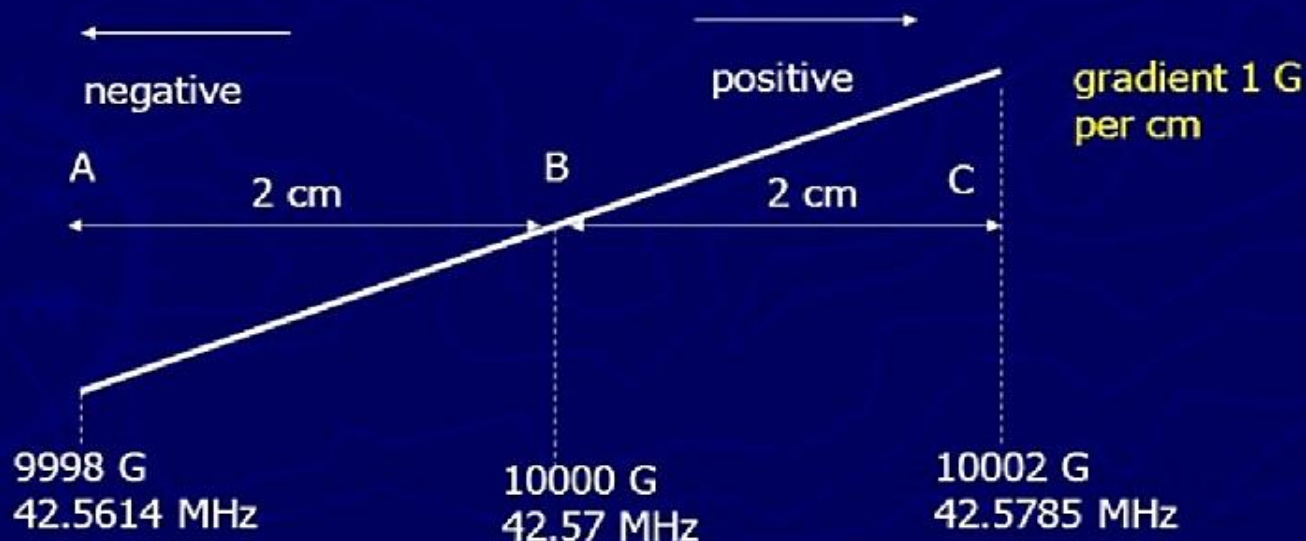
MRI Gradient Slew Rates Compared

Manufacturer	Model	Amplitude (mT/m)	Slew Rate (mT/m/ms)	Manufacturer	Model	Amplitude (mT/m)	Slew Rate (mT/m/ms)
GE	HiSpeed	23	77	Siemens	Avanto SQ-Engine	45	200
GE	EchoSpeed	23	120	Philips	Power	30	75
GE	Signa HD/HDxt	33	120	Philips	Master	30	150
GE	Signa HDe	33	50	Philips	Pulsar	33	80
GE	Optima 450w	34	150	Philips	Nova	33	160
Siemens	Harmony Turbo	20	25	Philips	Ingenia	45	200
Siemens	Harmony Sprint	30	75	Toshiba	Excelart AG	30	50
Siemens	Harmony Quantum	30	150	Toshiba	Vantage AGV	30	50
Siemens	Avanto Q-Engine	33	125	Toshiba	Vantage XGV	30	130

Larmor Equation: $\omega_0 = \gamma \cdot B_0$

Spatial encoding

- ▶ Magnetic field strength and therefore the precessional frequency of the nuclei situated in the long axis is different and is predictable.
- ▶ This is called **spatial encoding**



Larmor Equation: $\omega_0 = \gamma \cdot B_0$

Gradient coils type

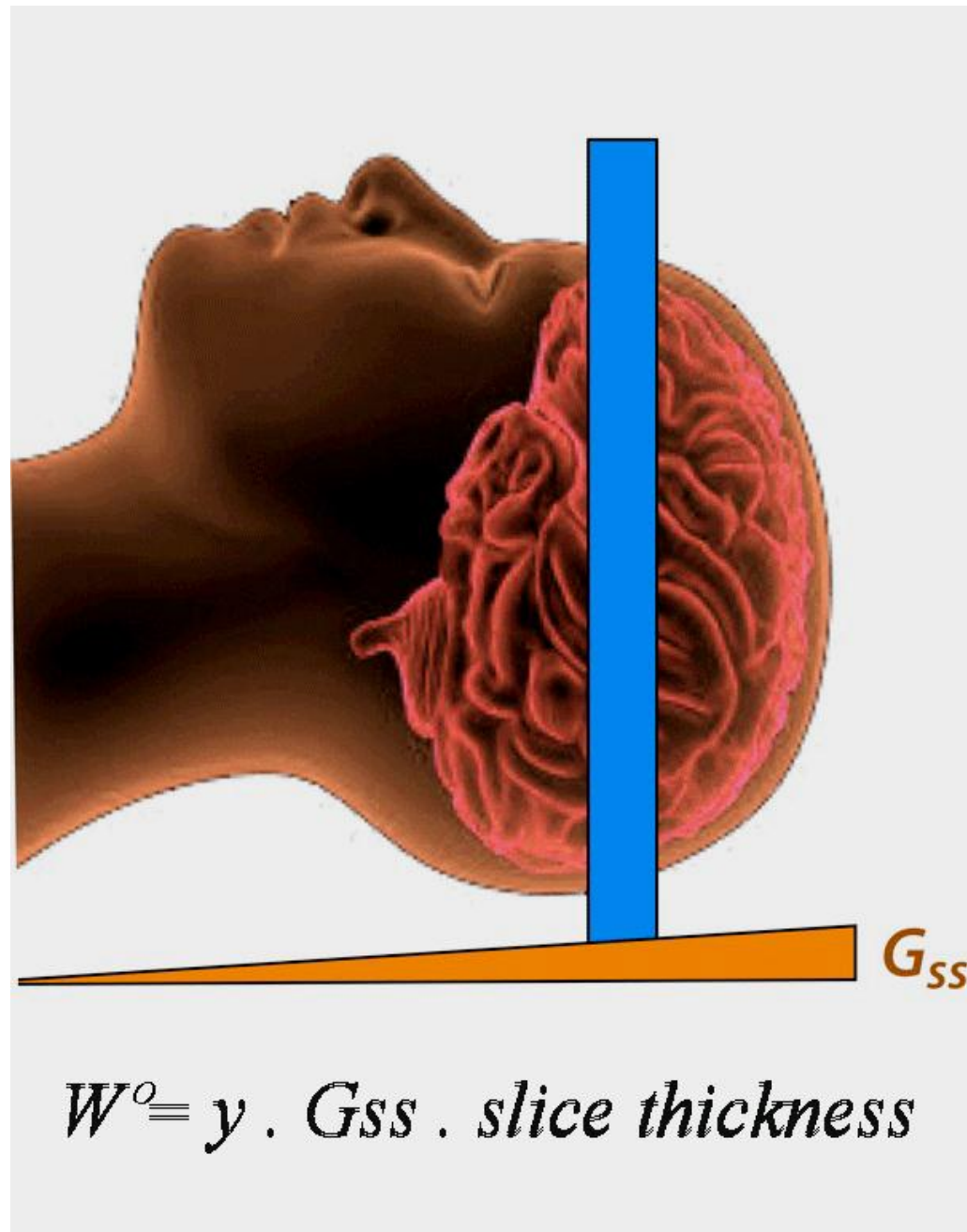
*First of all, a slice selection gradient (**GSS**) is used to select the anatomical volume of interest. Within this volume, the position of each point will be encoded vertically and horizontally by applying a phase encoding gradient (**GPE**), and a frequency-encoding gradient (**GFE**).*

Larmor Equation: $\omega_0 = \gamma \cdot B_0$

1- Slice Selection (GSS)

*The first step of spatial encoding consists in selecting the slice plane. To do this, a magnetic field gradient, the Slice Selection Gradient (GSS), is applied perpendicular to the desired slice plane (**Z direction**). This is added to B_0 , and the protons present a resonance frequency variation proportionate to GSS (Larmor equation). An RF Pulse is **simultaneously** applied, with the same frequency as that of the protons in the desired slice plane. This causes a shift in the magnetization of only the protons on this plane. As none of the hydrogen nuclei located outside the slice plane are excited, they will not emit a signal. The RF pulse associated with the slice selection gradient.*

Larmor Equation: $\omega = \gamma \cdot B_0$

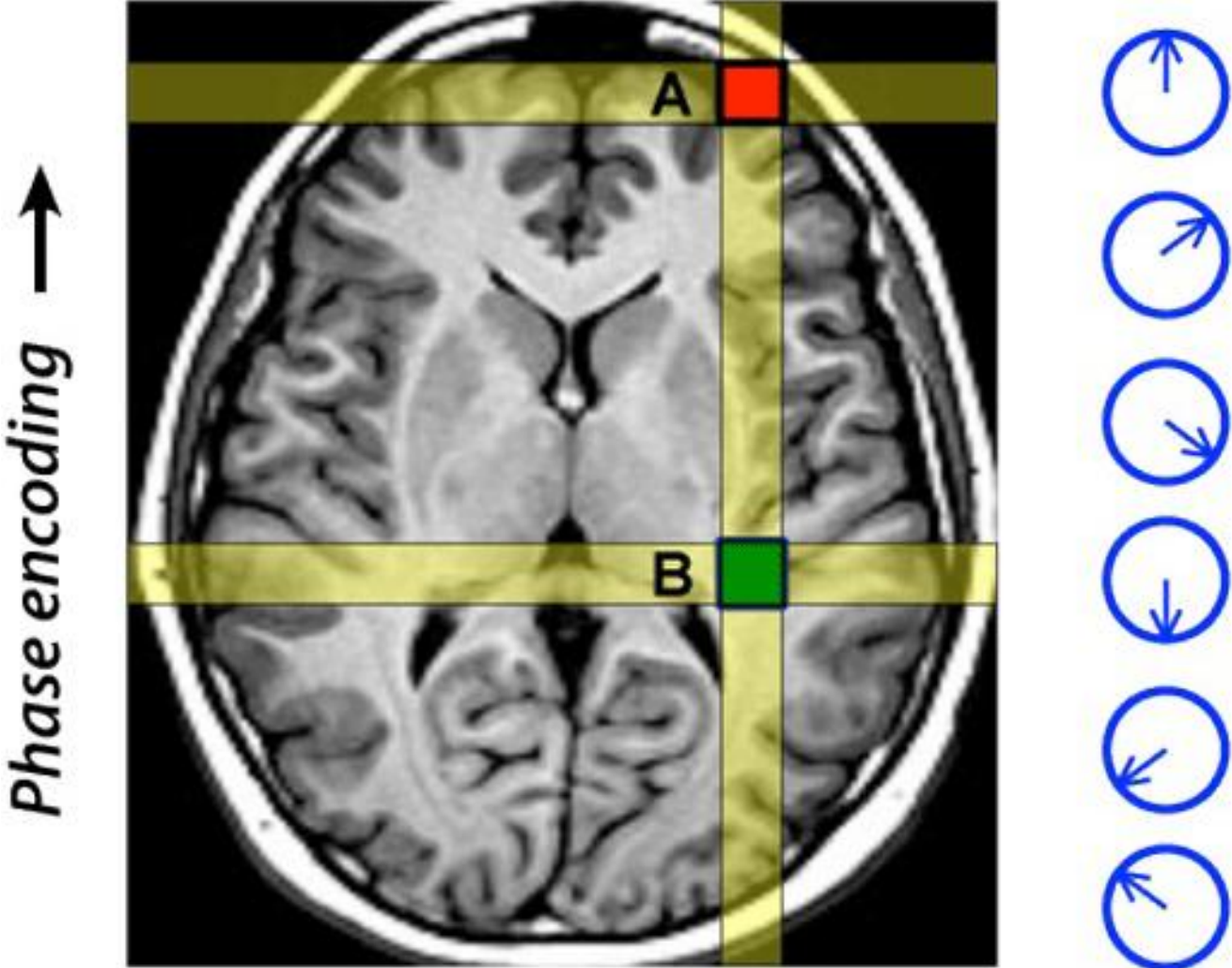


Larmor Equation: $\omega_0 = \gamma \cdot B_0$

2- Phase Encoding

*The second step in spatial encoding consists in applying a **phase encoding** (*modified*) gradient, which we will choose to apply in the vertical direction (**Y direction**). The phase encoding gradient (**GPE**) intervenes for a limited time period. While it is applied, it modifies the spin resonance frequencies, inducing dephasing.*

Larmor Equation: $\omega = \gamma \cdot B_0$



Larmor Equation: $\omega_0 = \gamma \cdot B_0$

3- Frequency Encoding

*the final step in spatial encoding consists in applying a **frequency encoding**(modified) gradient, when the signal is received, in the last direction horizontal (**X direction**). This modifies the Larmor frequencies in the horizontal direction throughout the time it is applied.*

This gradient is called

“read out” or “frequency encoding” gradient.

Larmor Equation: $\omega_0 = \gamma \cdot B_0$

